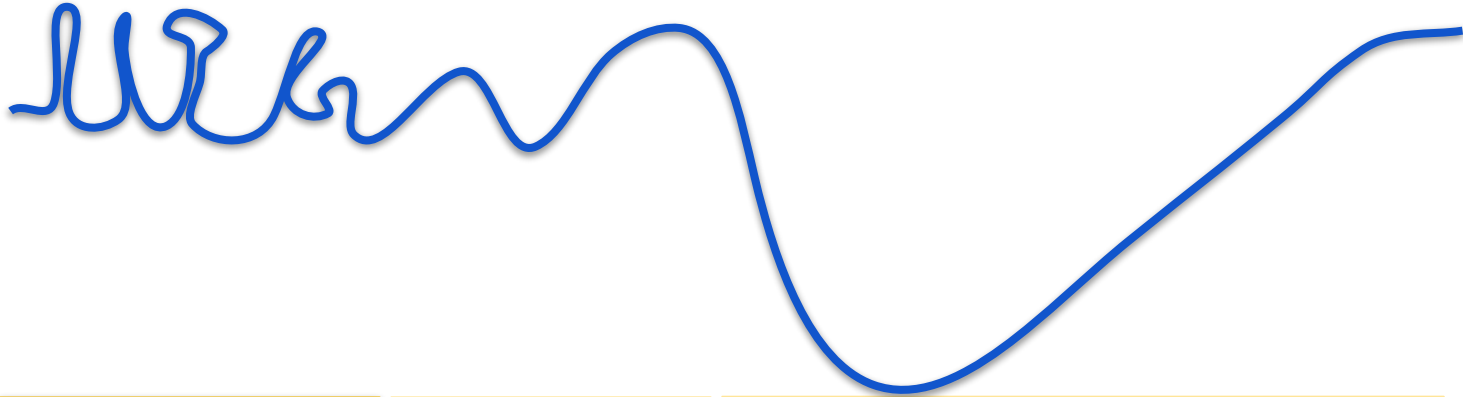


Computing with Signals



DA 623

Jan - May 2023

IIT Guwahati

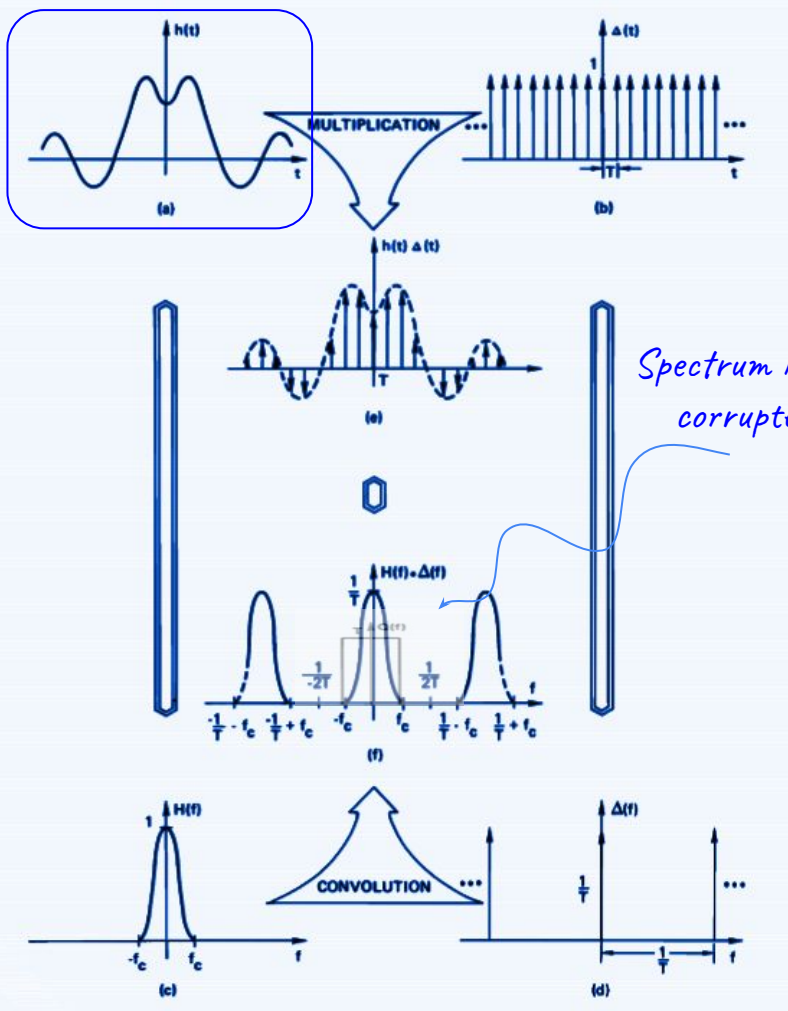
Instructors: Neeraj Sharma

Lecture-18-[22-Feb]

Sampling and Aliasing

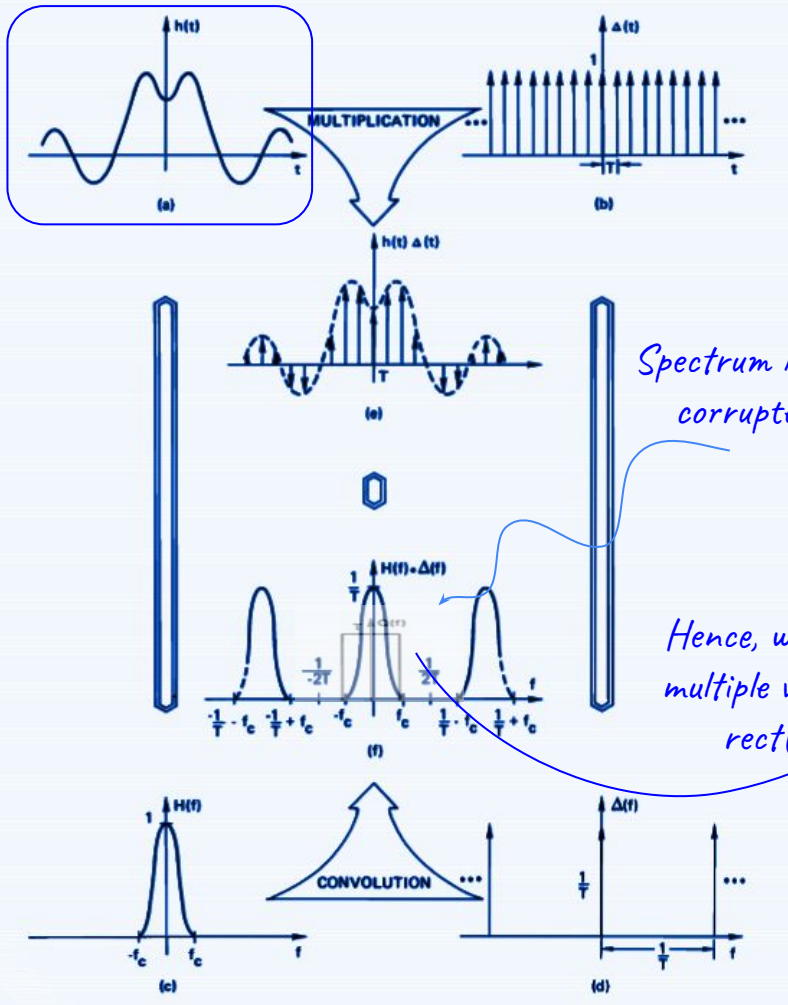
through visualizations

Acknowledgement: Multiple figures in this presentation are borrowed from the book "The Fast Fourier Transform and its Applications", by E. Oran Brigham. These figures are used here only for educational purpose.



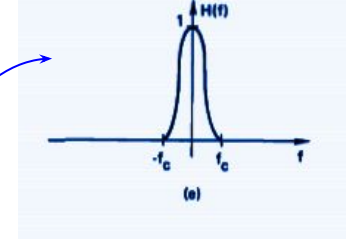
time-domain

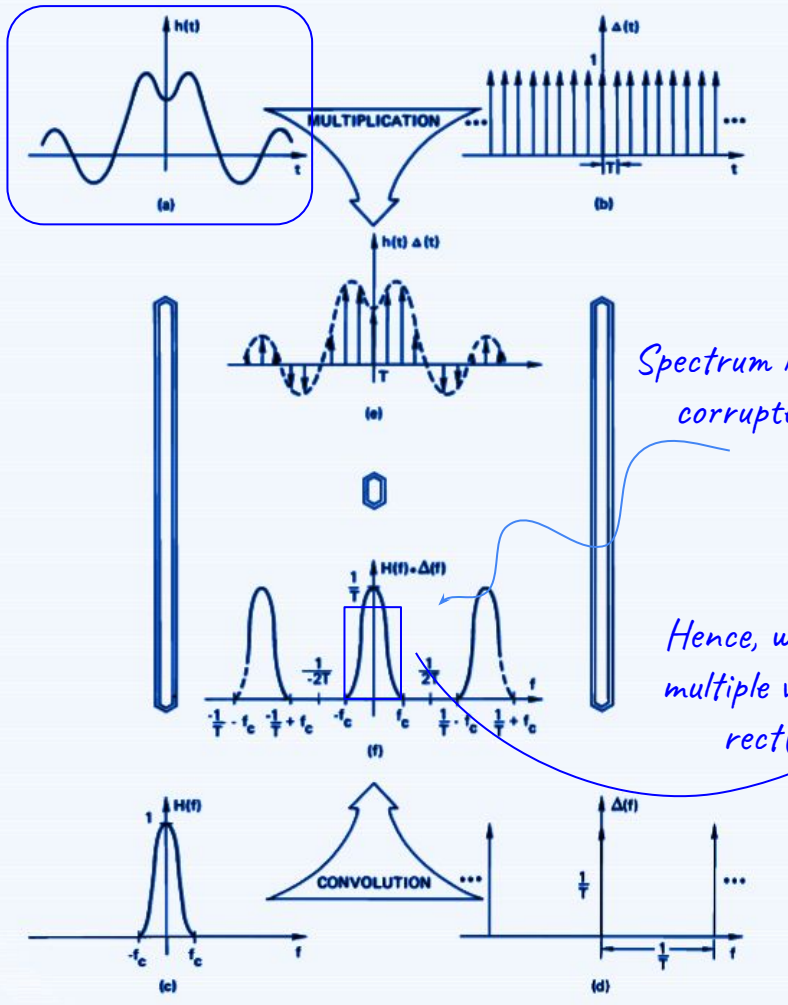
frequency-domain



time-domain

frequency-domain



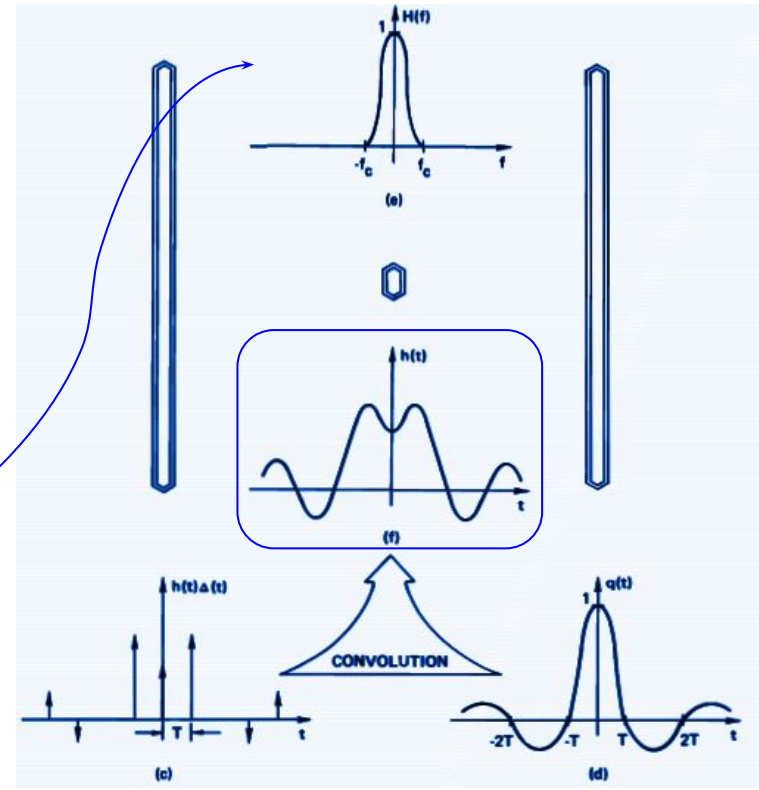


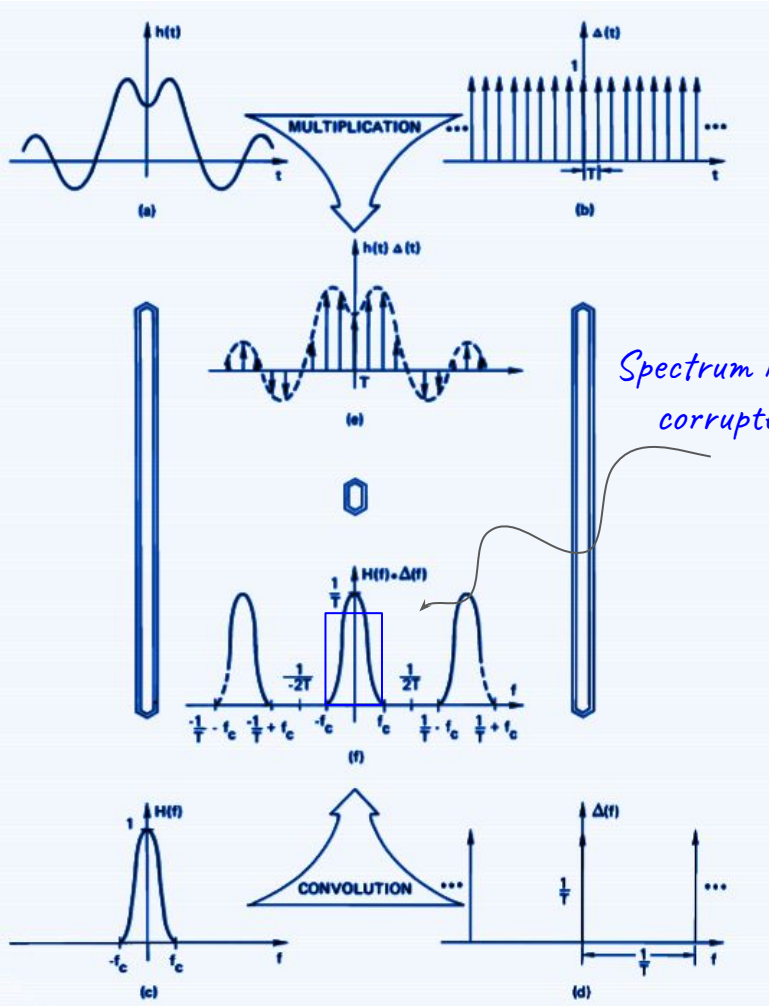
Spectrum is not corrupted!

Hence, we can multiply with a `rect()`

time-domain

frequency-domain

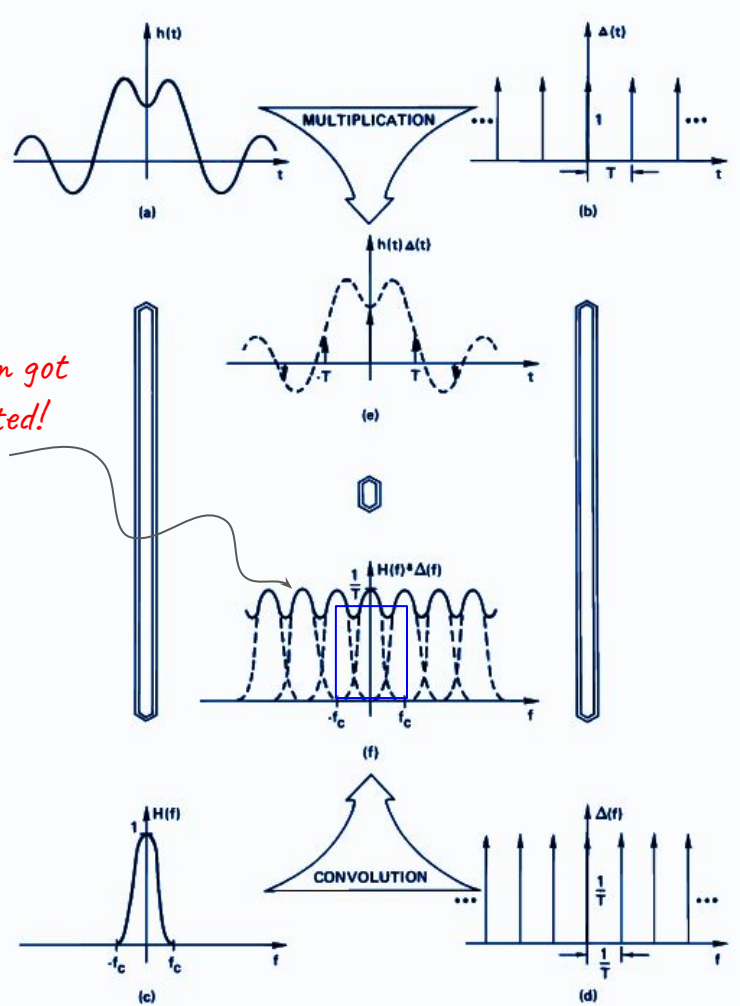




time-domain

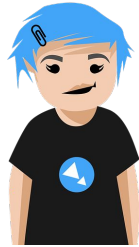
Spectrum got corrupted!

frequency-domain



A Sampling Story

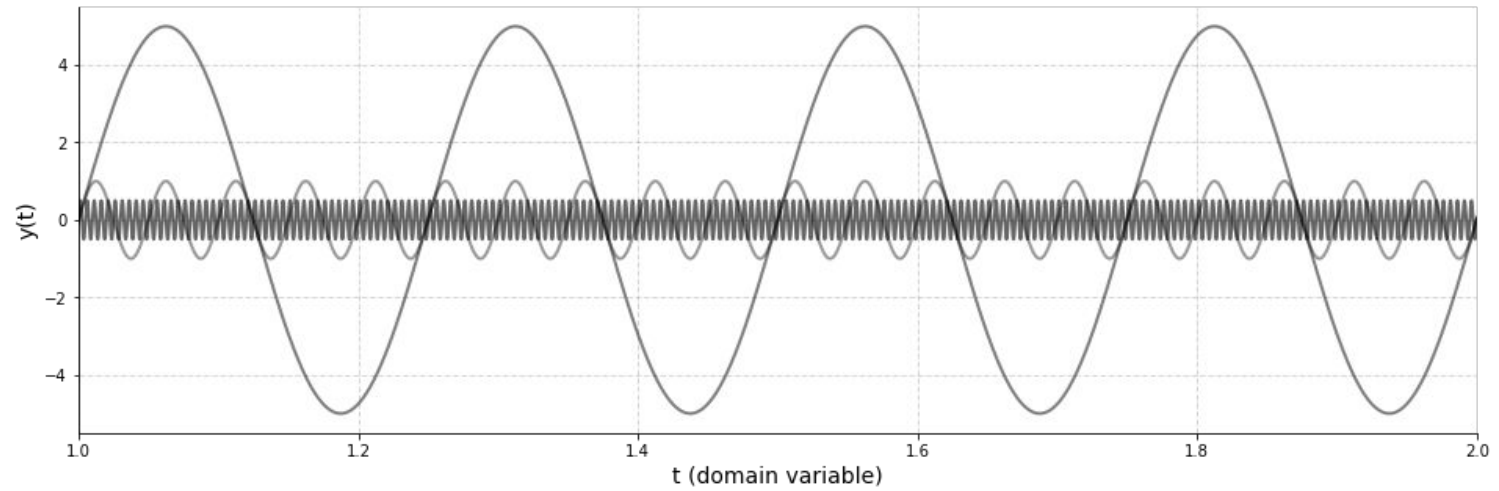
A Sampling Story







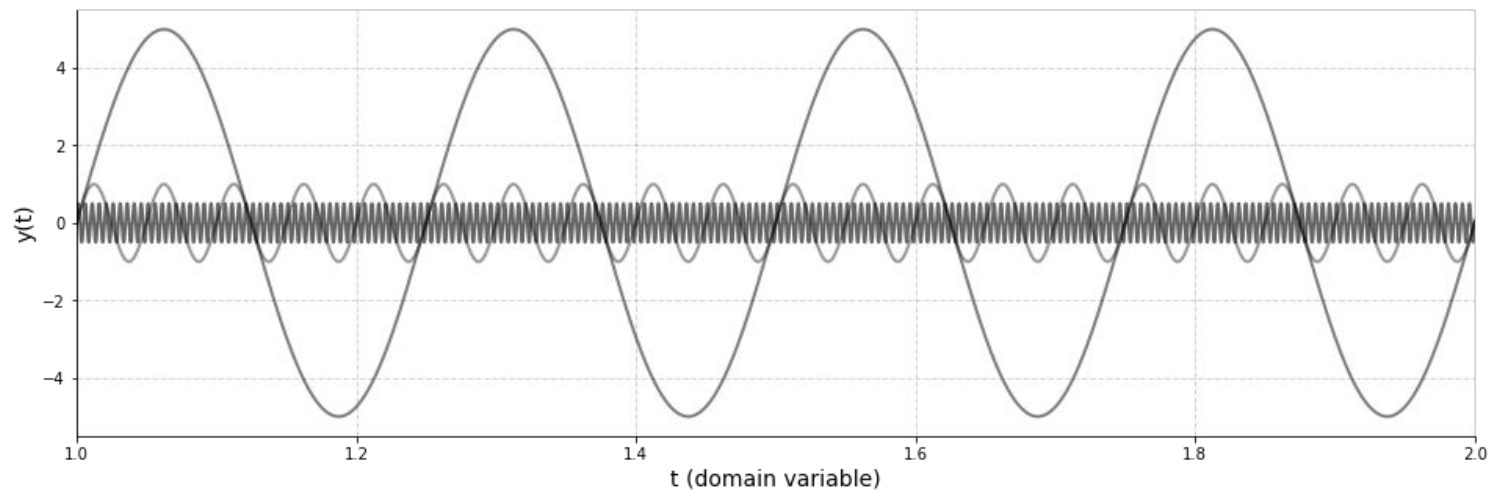
$$y_1(t), y_2(t), y_3(t)$$





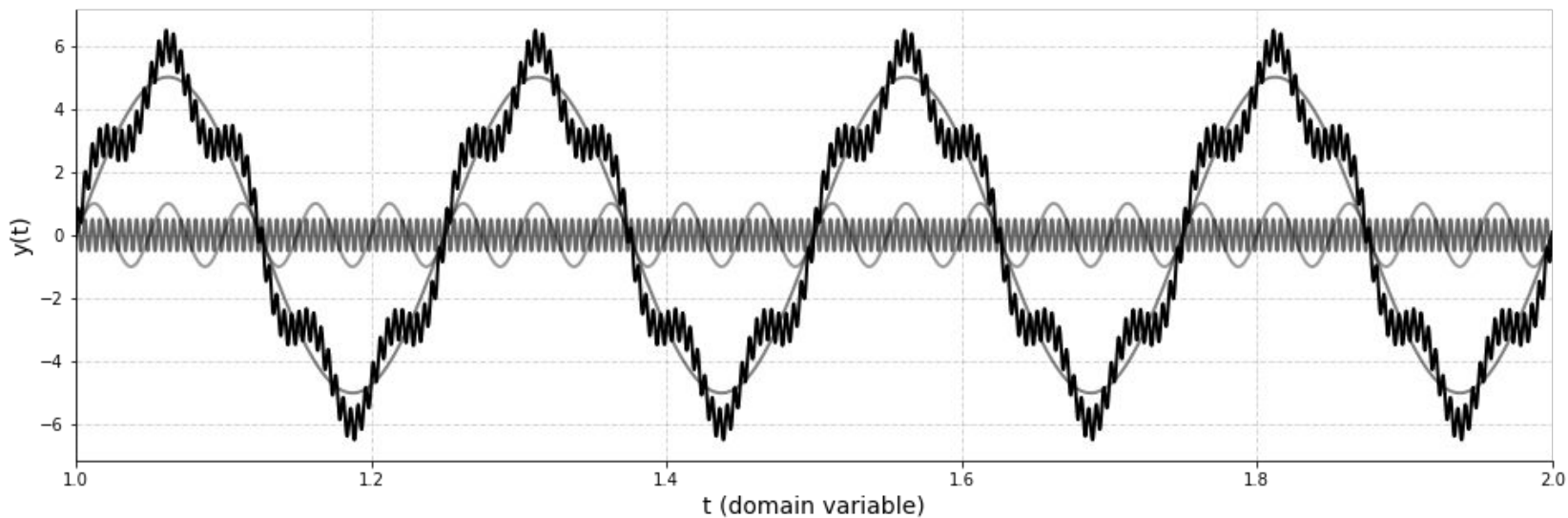
$$f_1 = 4 \text{ Hz}, f_2 = 40 \text{ Hz}, f_3 = 400 \text{ Hz}$$

$$y_1(t), y_2(t), y_3(t)$$





$$y(t) = y_1(t) + y_2(t) + y_3(t)$$





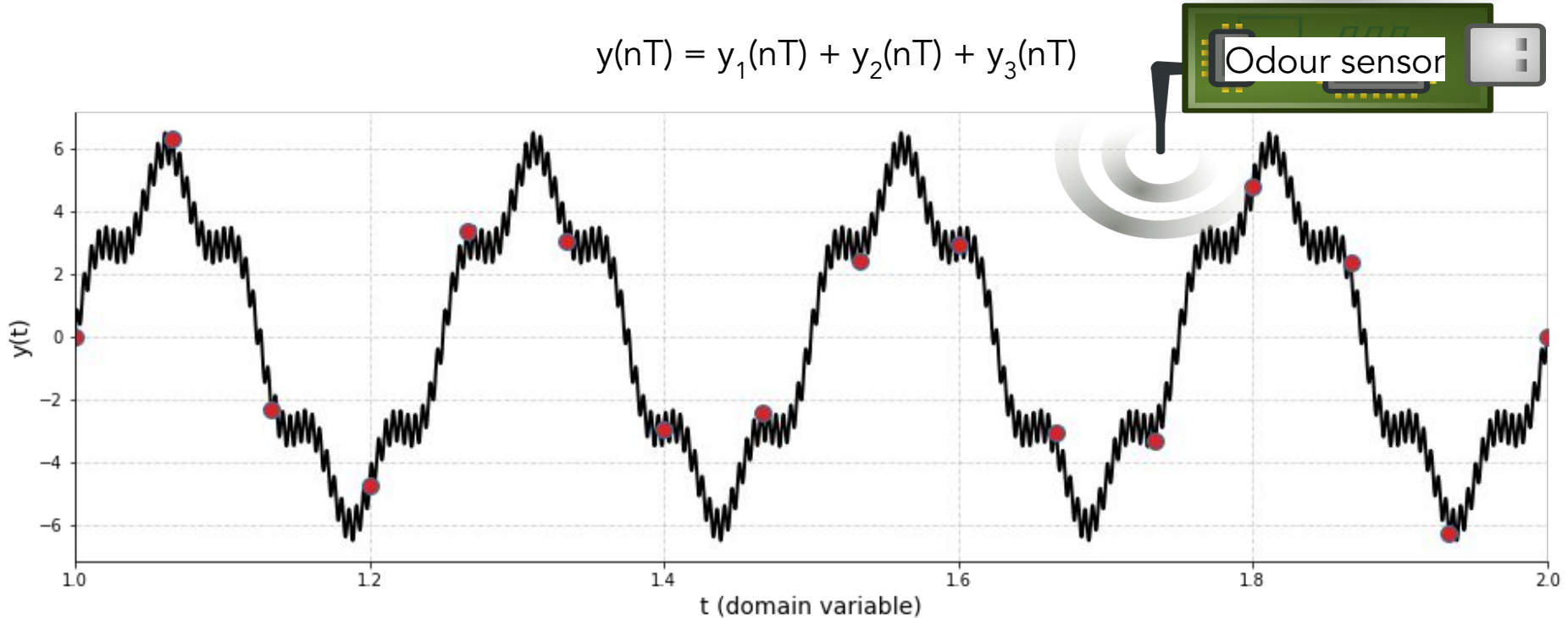
Odour sensor

A green callout box with a white border and a drop shadow. It contains the text "Odour sensor" in a white sans-serif font. To the right of the text is a small, stylized icon of a sensor device with a rectangular face and a vertical slot. A black pointer line extends from the top-left corner of the box towards the industrial facility in the background.

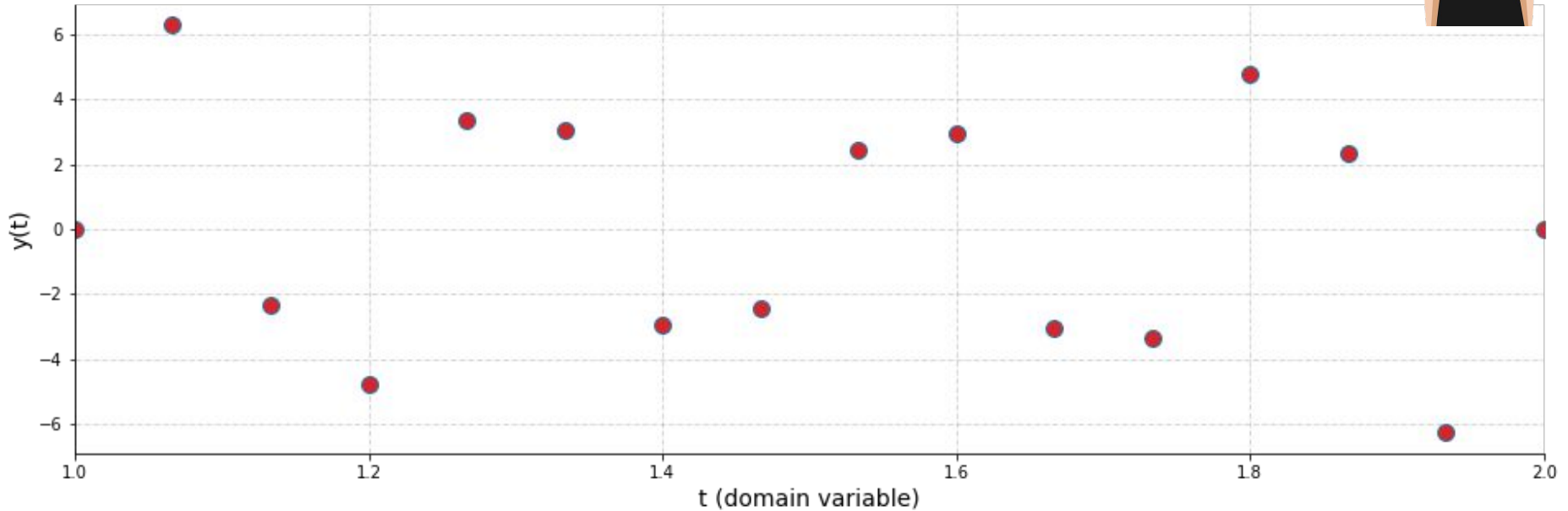
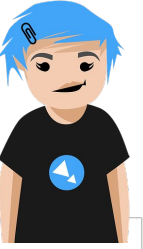
Assuming, T denotes the sampling period and n the sample index, we have:

- Hardware parameter: $f_s = 15$ Hz, that makes, $T = 1/f_s$

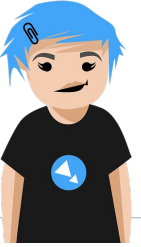
$$y(nT) = y_1(nT) + y_2(nT) + y_3(nT)$$



In hardware, data is stored as, $y(nT)$ where T is fixed by us in the hardware



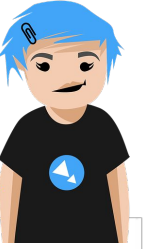
In hardware, data is stored as, $y(nT)$ where T is fixed by us in the hardware



\$ python



In hardware, data is stored as, $y(nT)$ where T is fixed by us in the hardware

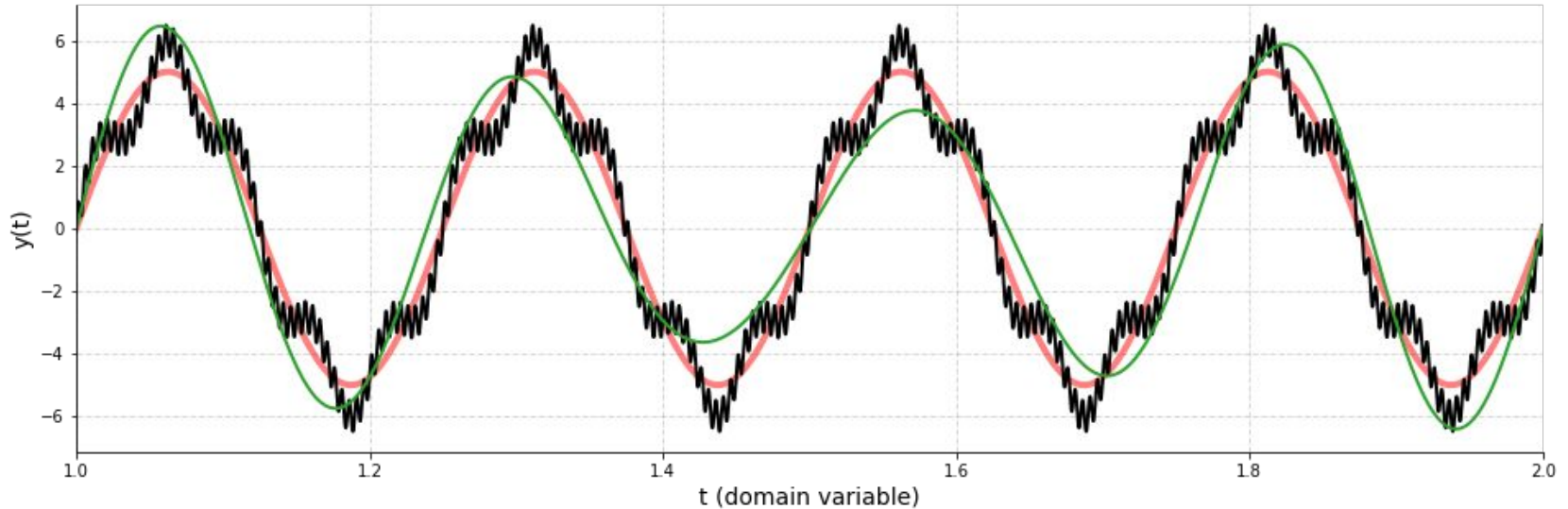


\$ python



$y_{\text{hat}}(t)$ obtained from $y(nT)$ via sinc interpolation

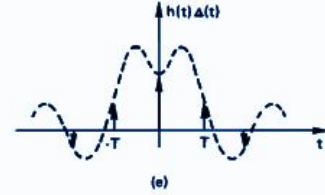
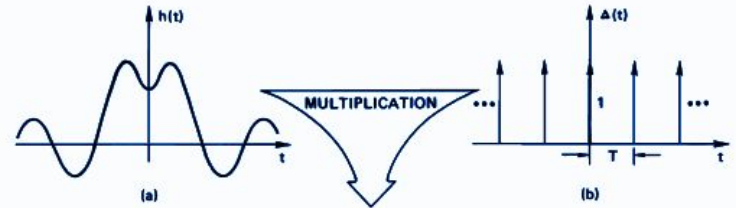
- Hardware parameter: $f_s = 15$ Hz, that makes, $T = 1/f_s$



1. Did it reconstruct $y(t)$?
2. If no, why?
 - A. Did it reconstruct $y_1(t)$ or $y_2(t)$ or $y_3(t)$? Explain.
 - B. What is this phenomenon called?
 - C. How to avoid it?

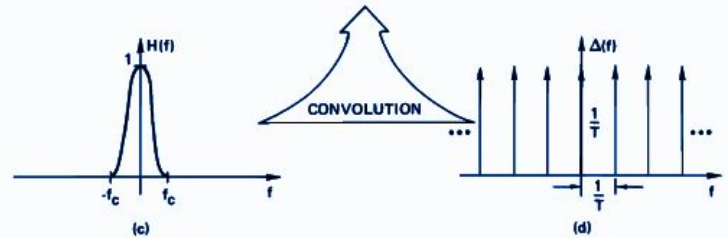
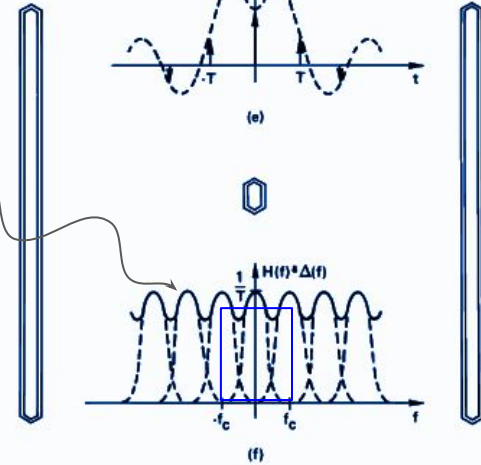
Aliasing

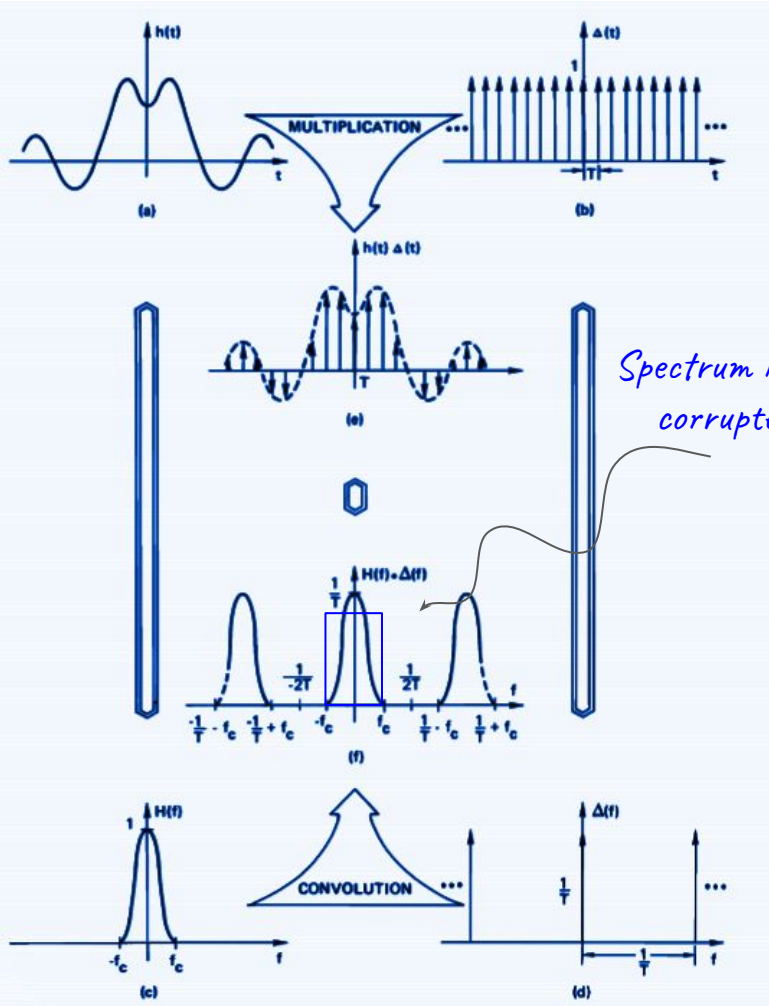
time-domain



frequency-domain

Spectrum got corrupted!



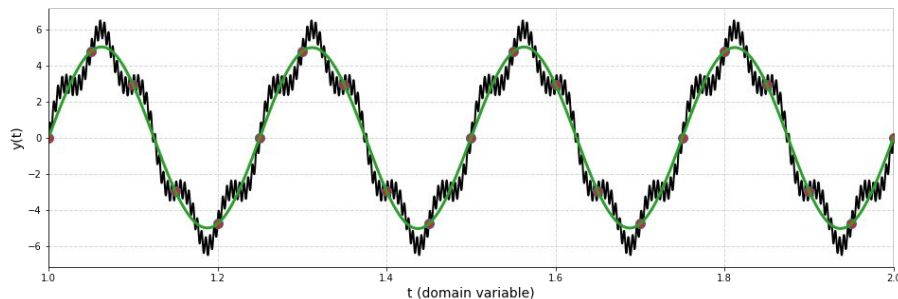


time-domain

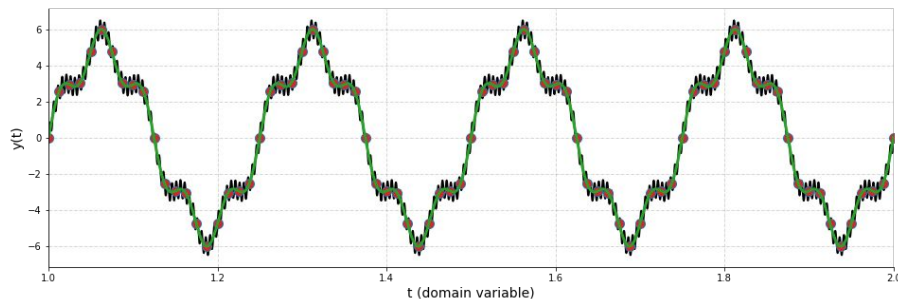
frequency-domain

Perfect reconstruction

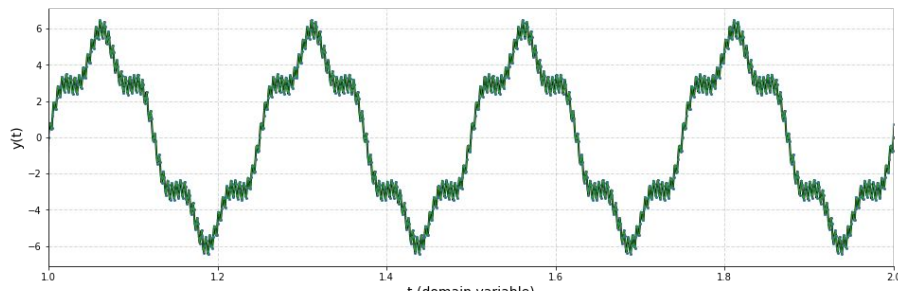
- $f_s = 20 \text{ Hz}$



- $f_s = 80 \text{ Hz}$



- $f_s = 1000 \text{ Hz}$

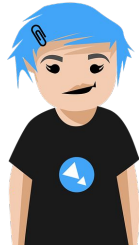


*For perfect
reconstruction:
obey Nyquist
rate*

$$f_s > 2 f_{\max}$$



A Sampling Story

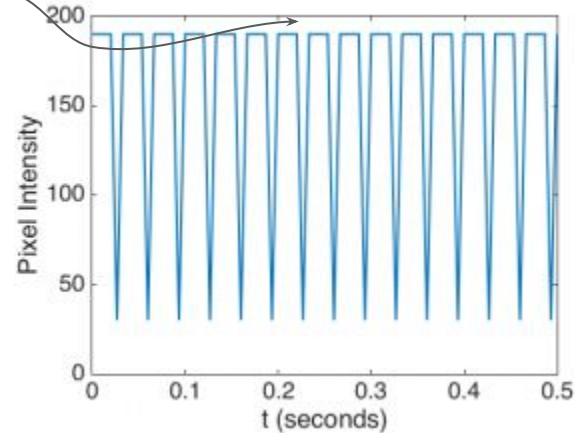
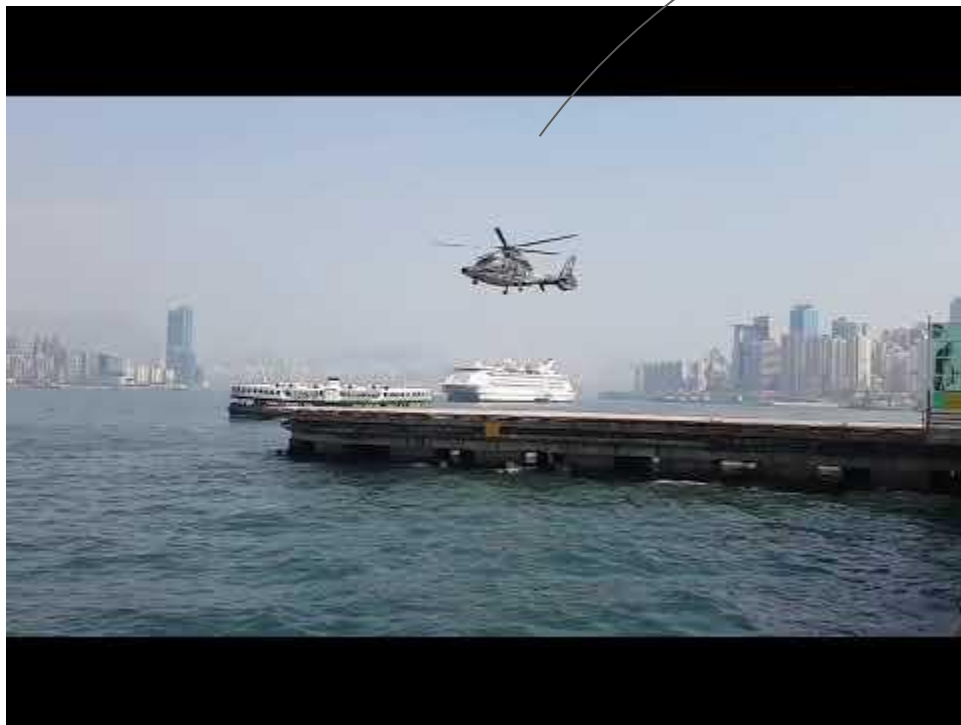


Moral of the story:

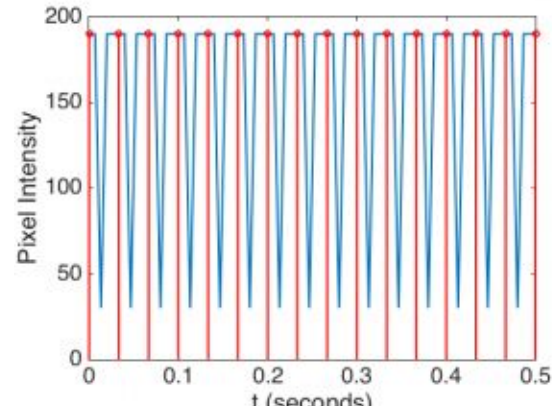
- Nature is continuous.
- Acquire domain knowledge.
- Check the sampling rate.



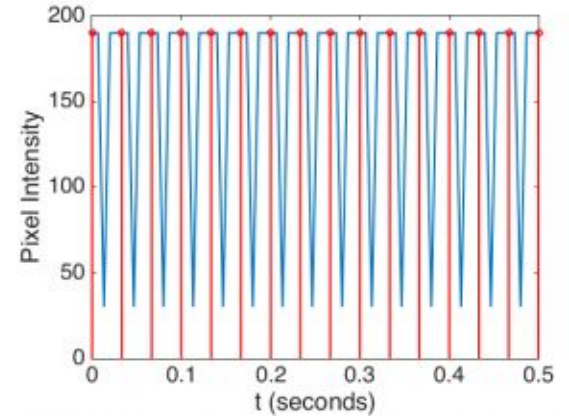
Value of intensity as a function of time on the camera pixel



The period of this signal corresponds to the rotor speed.



Value of intensity as a function of time on the camera pixel



The period of this signal corresponds to the rotor speed.

The camera samples this signal at a particular frame rate.



Summary

- Visualized sampling and interpolation
- Aliasing as folding of the spectrum
 - Results in corruption of the spectrum and hence of the reconstructed/interpolated signal
- Ways to avoid aliasing
 - Sample at higher and higher frequency
 - How do you decide? Physics? Experiments? Domain knowledge can help.
 - Use anti-aliasing filter
 - Don't capture the full spectrum but what whatever is captured is not corrupted
- Aliasing in real world - examples, video, images, sound and more